

Ma140a Probability

Lecture 5: Random variables

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Inverse image

Let $f : X \rightarrow Y$ be a function between set. We define the **inverse image** of a set $A \subset Y$ as

$$f^{-1}(A) := \{x \in X : f(x) \in A\}.$$

Remark that this gives a function $f^{-1} : 2^Y \rightarrow 2^X$.

Example

Let $\Omega = \{\square, \square\cdot, \square\cdot\cdot, \square\cdot\cdot\cdot, \square\cdot\cdot\cdot\cdot, \square\cdot\cdot\cdot\cdot\cdot\}$. Define $X : \Omega \rightarrow \mathbb{Z}$ as $X(\omega) = (\# \text{ of points})$, and $Y = X \pmod 2$. Then $Y^{-1}(0) = \{\square\cdot, \square\cdot\cdot\cdot, \square\cdot\cdot\cdot\cdot\cdot\}$.

Measurability

Let (X, \mathcal{F}) and (Y, \mathcal{G}) be measurable spaces. A function $f : X \rightarrow Y$ is called **measurable** (or \mathcal{F}/\mathcal{G} -measurable) if for all $G \in \mathcal{G}$, $F^{-1}(G)$ belongs to \mathcal{F} .

Remark: In this case, there is a map $f^{-1} : \mathcal{G} \rightarrow \mathcal{F}$.

Example

Let $\Omega = \{H, T\}^{\mathbb{N}} = \{\omega : \mathbb{N} \rightarrow \{H; T\}\} = \{(\omega_0, \omega_1, \dots) : \omega_i \in \{H, T\}\}$, and define $X_i : \Omega \rightarrow \mathbb{R}$ by

$$X_i(\omega) = \begin{cases} 1 & \text{if } \omega_i = H \\ 0 & \text{if } \omega_i = T \end{cases} .$$

What is the smallest σ -algebra on Ω that makes all $(X_i)_{i \in \mathbb{N}}$ measurable?

It must contain every set of the form $\{X_i = 1\}$... in fact, it is $\sigma(\{\{X_i = 1\}, i \in \mathbb{N}\})$.

Measurability (continued)

Let (X, \mathcal{F}) be a measurable space. For a real-valued function $f : X \rightarrow \mathbb{R}$, it is understood that \mathbb{R} is equipped with its Borel σ -algebra.

We denote by $m\mathcal{F}$ the set of real-valued measurable functions on (X, \mathcal{F}) . In turn, $b\mathcal{F}$ denotes the subset of bounded real-valued measurable functions.

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A function $f : X \rightarrow \mathbb{R}$ on a topological space $(X; \tau)$ is called Borel if it is $\sigma(\tau)/\mathcal{B}(\mathbb{R})$ -measurable.

Functoriality

Theorem

If $f : (X, \mathcal{F}) \rightarrow (Y, \mathcal{G})$ and $g : (Y, \mathcal{G}) \rightarrow (Z, \mathcal{H})$ are measurable maps, then $g \circ f : (X, \mathcal{F}) \rightarrow (Z, \mathcal{H})$ is measurable too.

Functoriality

Theorem

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Proof.

We can compose $g^{-1} : \mathcal{H} \rightarrow \mathcal{G}$ and $f^{-1} : \mathcal{G} \rightarrow \mathcal{F}$.

In other words, for any $H \in \mathcal{H}$, $g^{-1}(H) \in \mathcal{G}$, so $f^{-1}(g^{-1}(H)) \in \mathcal{F}$, and $f^{-1}(g^{-1}(H)) = (g \circ f)^{-1}(H)$. □

There's a category whose objects are measurable spaces and whose arrows are measurable maps.

Theorem (Williams, Prop. 3.2)

Let $h : X \rightarrow Y$ be a function.

- 1 h^{-1} preserves all set operations: for every index set A (of arbitrary cardinality), every collection $(E_\alpha)_{\alpha \in A}$, and any $E \subset Y$,
 - $h^{-1}(\bigcup_{\alpha \in A} E_\alpha) = \bigcup_{\alpha \in A} h^{-1}(E_\alpha)$
 - $h^{-1}(E^c) = (h^{-1}(E))^c$
 - $h^{-1}(\bigcap_{\alpha \in A} E_\alpha) = \bigcap_{\alpha \in A} h^{-1}(E_\alpha)$
- 2 Suppose (X, \mathcal{F}) and (Y, \mathcal{G}) are measurable spaces. Consider $\mathcal{C} \subset \mathcal{G}$ such that $\sigma(\mathcal{C}) = \mathcal{G}$. If for every $C \in \mathcal{C}$, $h^{-1}(C) \in \mathcal{F}$, then h is measurable.

Proof.

(1): Exercise.

For part (2), consider the collection \mathcal{E} of sets E such that $h^{-1}(E) \in \mathcal{F}$. By (1) it is a σ -algebra and by (2) it contains \mathcal{C} , hence it also contains \mathcal{G} . □

Two applications

Example

Let $Y = \mathbb{R}$ and $\mathcal{G} = \mathcal{B}(\mathbb{R})$. Then $\mathcal{G} = \sigma(\{(-\infty, c] : c \in \mathbb{R}\})$ so $h : X \rightarrow \mathbb{R}$ is measurable if $h^{-1}((-\infty, c]) \in \mathcal{F}$ for all $c \in \mathbb{R}$.

Corollary

If X, Y are topological spaces and $h : X \rightarrow Y$ is continuous, then h is also measurable.

Real-valued measurable functions form an algebra over \mathbb{R}

Theorem (Williams, 3.2)

For any $h_1, h_2 \in m\mathcal{F}$ and $\lambda \in \mathbb{R}$, one has

$$h_1 + h_2 \in m\mathcal{F}, \quad h_1 \cdot h_2 \in m\mathcal{F}, \quad \text{and} \quad \lambda h_1 \in m\mathcal{F}$$

Extended real line

It is convenient to introduce the extended real line $\bar{\mathbb{R}} = \mathbb{R} \cup \{-\infty, +\infty\}$.

This is a totally ordered set, that we equip with the order topology, which is generated by the rays $(a, +\infty]$ and $[-\infty, a)$. As a topological space, it is compact and homeomorphic to $[0, 1]$.

The rays $(a, +\infty]$ are neighborhoods of $+\infty$, and similarly the rays $[-\infty, a)$ are neighborhoods of $-\infty$.

$\mathcal{B}(\bar{\mathbb{R}})$ is the Borel σ -algebra generated by this topology.

$\pi(\bar{\mathbb{R}}) = \{ [-\infty, c] : c \in \bar{\mathbb{R}} \}$ is a π -system that generates $\mathcal{B}(\bar{\mathbb{R}})$.

Measurability of limits

Theorem (Williams, 3.5)

Let $(h_n)_{n \in \mathbb{N}}$ be a sequence of elements of $m\mathcal{F}$. Then $\inf h_n$, $\sup h_n$, $\liminf h_n$ and $\limsup h_n$ are measurable functions (valued in $\bar{\mathbb{R}}$). Further,

$$\{\omega \in \Omega : \lim h_n(\omega) \text{ exists in } \mathbb{R}\} \in \mathcal{F}.$$

Proof.

For inf: $\{\inf h_n \geq C\} = \cup_{n \in \mathbb{N}} \{h_n \geq c\}$. □

Example

Let $\Omega = \{H, T\}^{\mathbb{N}} = \{\omega : \mathbb{N} \rightarrow \{H; T\}\} = \{(\omega_0, \omega_1, \dots) : \omega_i \in \{H, T\}\}$, and define $X_i : \Omega \rightarrow \mathbb{R}$ by

$$X_i(\omega) = \begin{cases} 1 & \text{if } \omega_i = H \\ 0 & \text{if } \omega_i = T \end{cases}.$$

$$\mathcal{F} = \sigma(\{\{X_i = 1\}, i \in \mathbb{N}\}).$$

Then $S_n = X_1 + \dots + X_n$ measurable for every $n \in \mathbb{N}^*$.

We conclude that

$$\Lambda = \{\omega \in \Omega : S_n(\omega)/n \rightarrow p\} = \{\liminf S_n/n = p\} \cap \{\limsup S_n/n = p\}$$

belongs to \mathcal{F} i.e. it is measurable.

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Random variables

Let (Ω, \mathcal{F}, P) be a probability space and (E_X, \mathcal{F}_X) be a measurable set. In probabilistic terminology, a measurable function $X : (\Omega, \mathcal{F}) \rightarrow (E_X, \mathcal{F}_X)$ is an **E_X -valued random variable**.

When $E_X = \mathbb{R}$, we simply say *random variable*.

Remark

For some authors (e.g. Omer Tamuz) a random variable is an equivalence class of measurable functions, under $f \sim g$ iff $P(f \neq g) = 0$. The problem is that, under this definition, it does not make sense to talk about $f \geq 0$ or f continuous, etc. One has to go back and forth between equivalence classes and representatives.

As suggested by the examples above, Ω does not have to be a numeric space. The random variables turn the possible outcomes $\omega \in \Omega$ into numbers, that can be combined using arithmetic operations, etc.

The algebra generated by X , denoted $\sigma(X)$, is the σ -algebra generated by $X^{-1}(\mathcal{F}_X) := \{X^{-1}(F) : F \in \mathcal{F}_X\}$. This is the smallest σ -algebra that makes X measurable. More generally:

Definition

Given a collection $(Y_\alpha : \Omega \rightarrow (E_\alpha, \mathcal{F}_\alpha), \alpha \in A)$ of maps on a set Ω into measurable spaces $(E_\alpha, \mathcal{F}_\alpha)$,

$$\sigma(Y_\alpha : \alpha \in A) := \sigma\left(\bigcup_{\alpha \in A} Y_\alpha^{-1}(\mathcal{F}_\alpha)\right)$$

is the smallest σ -algebra that makes all Y_α measurable simultaneously.

$\sigma(Y_\alpha : \alpha \in A)$ contains all the events that can be defined in terms of Y_α s, such that $\{a \leq Y_\alpha \leq b, c \leq Y_\beta \leq d\}$, etc.

Law and distribution function

(Ω, \mathcal{F}, P) probability triple, $X : \Omega \rightarrow (E_X, \mathcal{F}_X)$.

$$\mathcal{F}_X \xrightarrow{X^{-1}} \mathcal{F} \xrightarrow{P} [0, 1]$$

$$A \longmapsto \{X \in A\} \longmapsto P(X \in A)$$

Remember that $\{X \in A\} = \{\omega \in \Omega : X(\omega) \in A\}$.

The law of X is the measure $L_X = P \circ X^{-1}$ defined on (E_X, \mathcal{F}_X) . It is a probability measure.

When $E_X = \mathbb{R}$, we saw that L_X is uniquely determined by $F_X : \mathbb{R} \rightarrow [0, 1]$ such that $F_X(x) = L_X((-\infty, x]) = P(X \leq x)$.

F_X is called the **cumulative distribution function** (cdf) of X .

Theorem (Williams 3.10)

Suppose F is the distribution function of some real-valued random variable. Then

- 1 $F : \mathbb{R} \rightarrow [0, 1]$ is nondecreasing.
- 2 $\lim_{x \rightarrow -\infty} F(x) = 0$ and $\lim_{x \rightarrow +\infty} F(x) = 1$.
- 3 F is right continuous.

Proof.

The first follows from the monotonicity of P under inclusions, the second from the monotone-convergence properties of measures, and the third because

$$P(X \leq x + 1/n) \downarrow P(X \leq x).$$



Given a function F that satisfies these properties, one can construct an X whose cdf is F (Skorokhod representation, Williams 3.12).

Discrete variables

Suppose F_X is piece-wise constant, with discontinuities at $\Lambda = \{x_1, x_2, \dots\}$ (exercise: there is at most a countable number of such discontinuities).

For $x \in \Lambda$, set

$$p(x) = F(x) - \lim_{x \rightarrow x^-} F(x).$$

Then $\sum_{x \in \Lambda} p(x) = 1$. This p is called a **probability mass function**.

Example

$\Lambda = \{0, 1, 2, \dots, n\}$ and $p(k) = \binom{n}{k} p^k (1-p)^{n-k}$ defines a **binomial** distribution of parameter $p \in [0, 1]$.

Example

$\Lambda = \mathbb{N} = \{0, 1, 2, \dots\}$ and $p(k) = \frac{\lambda^k e^{-\lambda}}{k!}$ defines a **Poisson** distribution of parameter $\lambda > 0$.

Continuous variables

Suppose that $F(x) = \int_{-\infty}^x f(t) dt$ for some integrable function f .

By monotonicity of F , f must be positive.

And since $\lim_{x \rightarrow +\infty} F(x) = 1$, $\int_{-\infty}^{+\infty} f(x) = 1$.

f is called a probability density function.

Example

$f(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2\right)$ defines a **normal** distribution of mean $\mu \in \mathbb{R}$ and standard deviation $\sigma > 0$.

Example

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0, \\ 0 & x < 0. \end{cases}$$

defines an **exponential** distribution of parameter $\lambda > 0$.